The Lunar Nobility Vehicle (LNV)

by

LOCKHEED MARTIN



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Defining a New Era of Space Mobility

Unlocking the Lunar Surface for Science & Industry

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Space Heritage

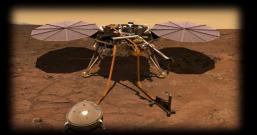


Lockheed is responsible for engineering many of humanity's boldest and most challenging space missions

Experienced Team

Established Facilities

Flight-Proven Subsystems



OSIRIS-REx

InSight Mars Lander





The Next Generation Of Lunar Rover



Commercial Lunar Mobility & Mission Support Services

Long Range, High Data Rate, Multi-Mission Support

Priced to Expand Access and Enable Impactful New Missions

Advance Space Science Unlock the Lunar Economy Alleviate Customer Infrastructure Needs

Explore New Possibilities

Unique Capability

Far Side and Permanently Shadowed Operations

Over 1,000 km Range per Lunar Day

1,600 kg+ Surface Payload Capacity

Robotic Arm with 70 kg+ Capacity and 2.5 m Reach

50 Mbps Data Downlink Rate to Earth

Robust Native Sensor Package

Launching to the Moon in 2027



Explore the Moon



360° Illumination

Stills, Video, and Tessellated 3D Models



VIS/NIR HD & 4K Cameras Radar & Neutron LiDAR Spectrometer

More than 10 km² of Mapping Per Lunar Day



Spudis





Survive The Darkness

Vehicle Designed to Survive the Full Lunar Night and Support Payloads Throughout

Continuous Lunar Night Payload Power Availability for Year-Long Mission Operations

> Muti-Day Operational Capacity in Permanently Shadowed Regions





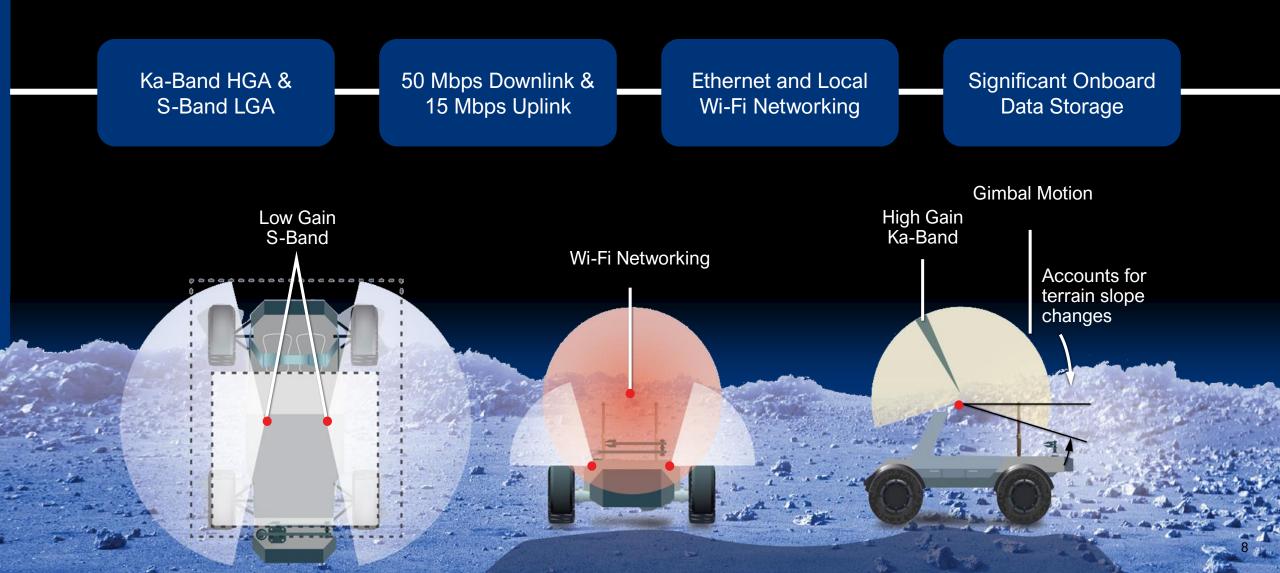
Lunar Night

Lunar Day

40 80 120 160 200 240 280 320 360 400 к -233 -193 -153 -113 -73 -33 7 47 87 128 с Surface Temperature Data From LRO & Diviner

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Meaningful Data Collection & Transmission



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Simplify Development

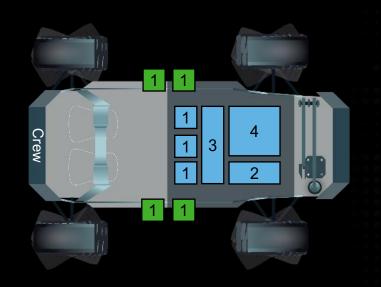
Standardized, Multipurpose Payload Support Configuration

Expandable Building-Block Model for Large Payloads

LM-Provided Interface Plates to Streamline Manufacturing

Payload Bed and Side-Slung Slots Available

Customizable for Specific Needs



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Single-Slot Universal Payload Adapter System (UPAS)

Standard Specs:

Land 35 kg Mass Support 70 kg+ Mass on Lunar Surface

Wi-Fi & Ethernet

Vehicle Data Access

28 & 120 VDC Power

Survive the Night Support Robotic Arm Interface

300 mm

500 mm

300 mm

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Imagine New Possibilities

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Investigate, Explore and Experiment

- Multispectral Surface Mapping
- Sample Analysis
- Close-Proximity Asset Imaging
- Long-Term Lunar Biology
- Deep Space Observation
- Mobile Space Situational Awareness
- Low-Gravity Manufacturing
- Lunar Geology & Planetary Science
- > Survivability Testbed
- Cinematic Event Capture
- Lunar Gravity & Magnetism
- Permanent Habitat Scouting & Staging

Prospect, Mine, and Survey

- Mobile Power & Comms Network Services
- Surface Spectrometry
- Core Sampling
- Regolith Drilling
- Load Carrying
- High Fidelity Resource Ground Truth
- Resource Extraction & Processing
- Shadowed Region & Lava Tube Exploration
- Refueling Demonstrations
- Volatiles & Rare Resource Sensing

Transport and Deliver

- Asset Relocation
- Sample Collection
- Crew Transportation
- > 3rd Party Lander Unloading
- Cargo Hauling Heavy Mass Lunar Surface Landing
- Sample Flagging for Crew
- Microrover Positioning & Sustained Support
- Critical Infrastructure Emplacement
- Geophysical Instrumentation Delivery

Construct, Service, and Assemble

- Landing Pad Preparation
- Asset Rescue & Maintenance
- Landing Zone Mapping
- Power, Transportation, PNT, and Comms Network
 Development
- Habitat Construction
- > Additive Manufacturing
- Recycling & Asset Reconstitution

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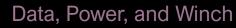
Mission: Lava Tube Explorer

- Mission Duration:
 - ➢ 300 Hours
- Objectives:
 - Deliver Lava Tube Rover to an Opening in the southern Mare Australe
 - Provide Data & Power to Lava Tube Rover
 - Transmit 500 GB of Lava Tube Mapping & Geology Data
- Distance Traveled:
 - ➤ 5 km

Mission Key



Lava Tube Rover



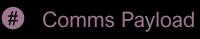


Mission: Lunar South Pole

- Mission Duration:
 - ➤ 180 Hours
- Objectives:
 - Map Shackleton Crater Rim
 - Deliver Three Comms Payloads
 - Passive Magnetotelluric Sounding
- Distance Traveled:
 - ➢ 500 km

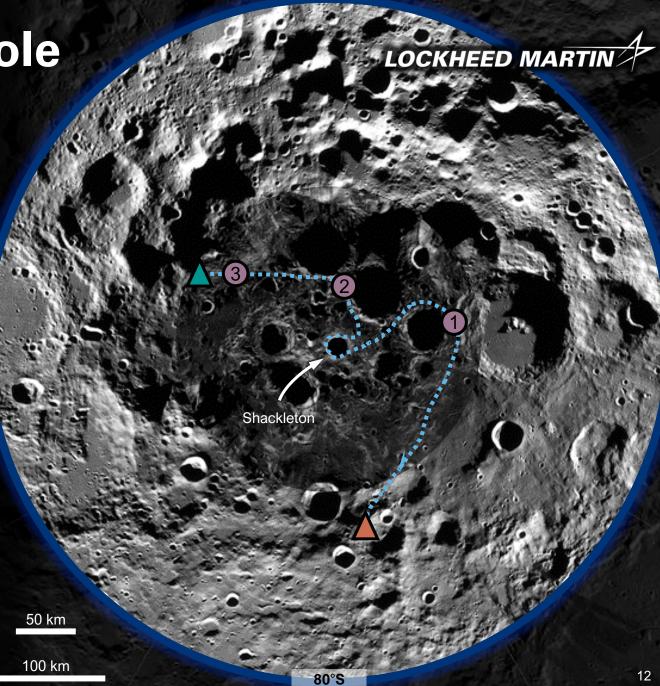
Mission Key







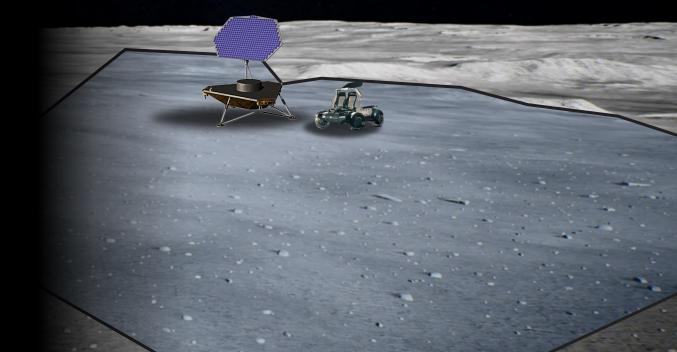
End Point



Mission: Lander Staging & Inspection

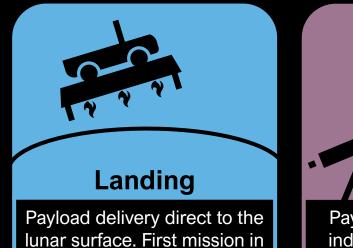


- Mission Duration:
 - ➤ Two Lunar Days
- Objectives:
 - Scout Landing Zone for Hazards
 - Prepare Landing Zone Terrain
 - Provide Lander with PNT Beacon
 - Film Lander Descent with 4K Camera
 - Close-Proximity Post-Descent Lander Inspection
 - Offload Lander Payloads into LMV Payload Bed
 - Depart Landing Zone
- Distance Traveled:
 - ➢ 50 km



Basic Services





2027.



Payloads that collect data independent of the LMV's primary tasked missions. Transportation & Active Payloads

Payload missions that require specific tasking including asset delivery, surface interactions, robotic arm operations, or a specific location.



Mapping and imaging missions using native LMV sensors including cameras, LiDAR, radar, and neutron spectrometer.

