

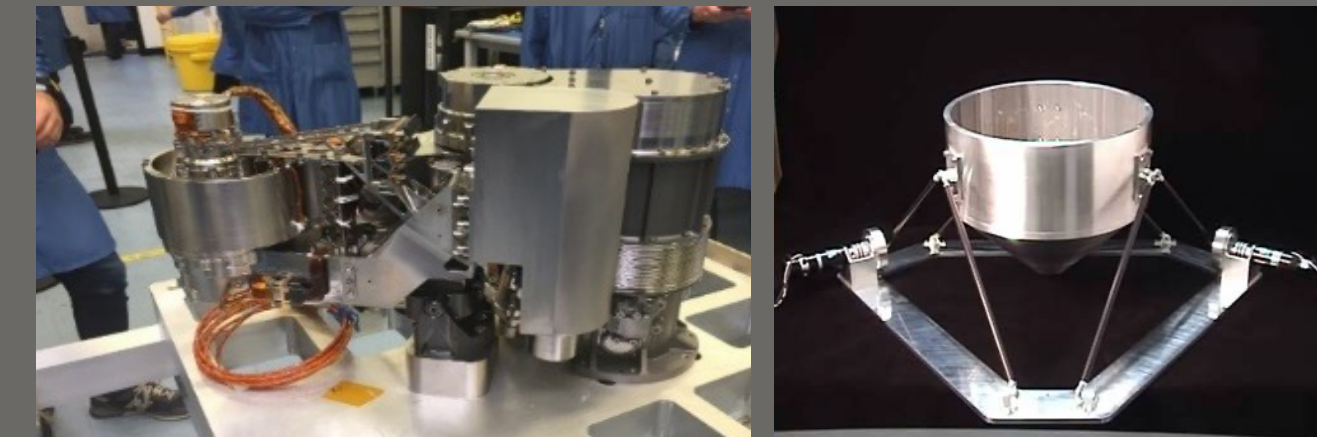


Low-Cost Robotics for Lunar Science and Exploration

Lunar Surface Innovation Consortium, Fall Meeting, 3-4 November 2021

Atif M. Qureshi, *Principal Robotics Engineer, Maxar*

World Leader in Space Robotics for 20+ Years



Company

Overview

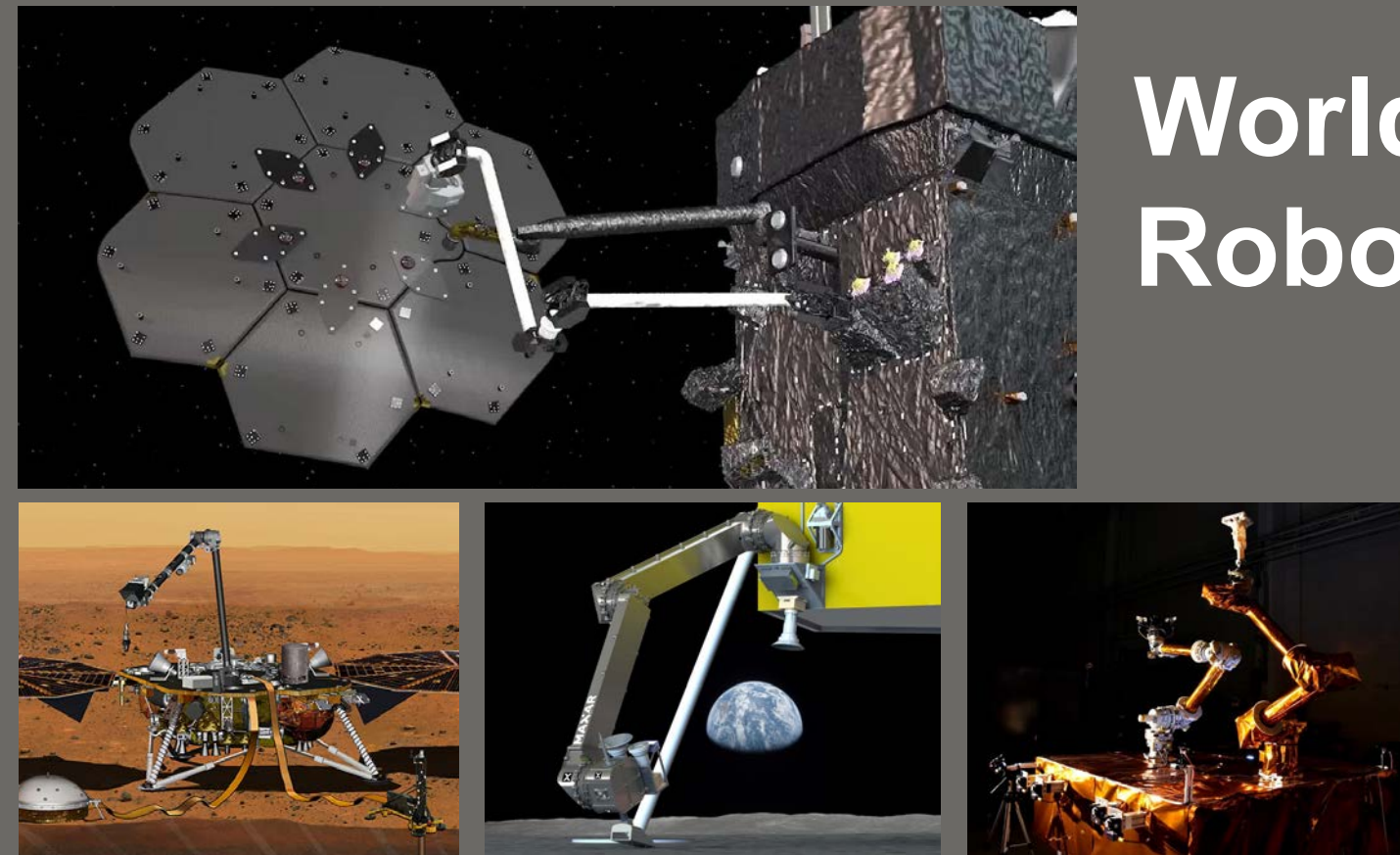
A Versatile Line of Actuator Options



60+ Years of Reliable Space Systems, Power and Communications

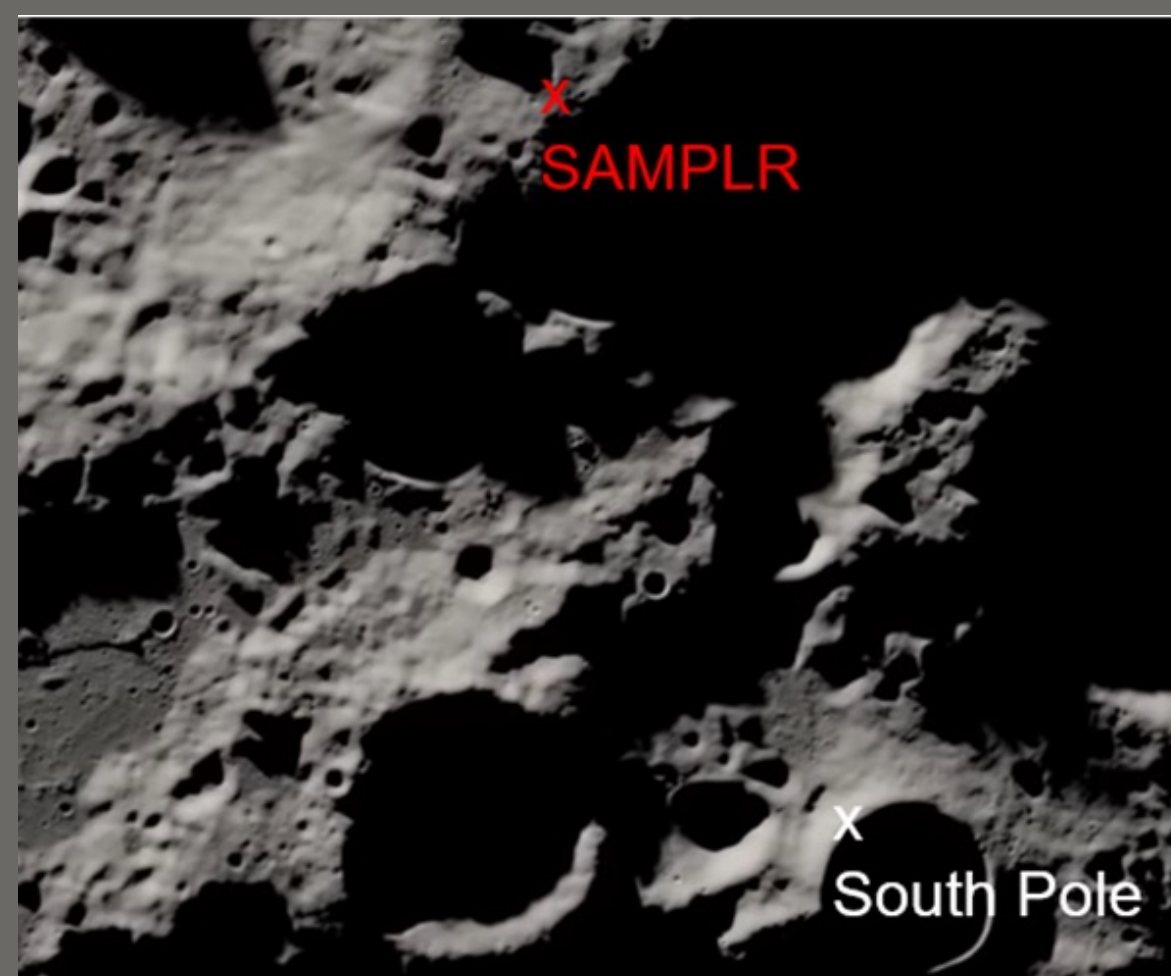
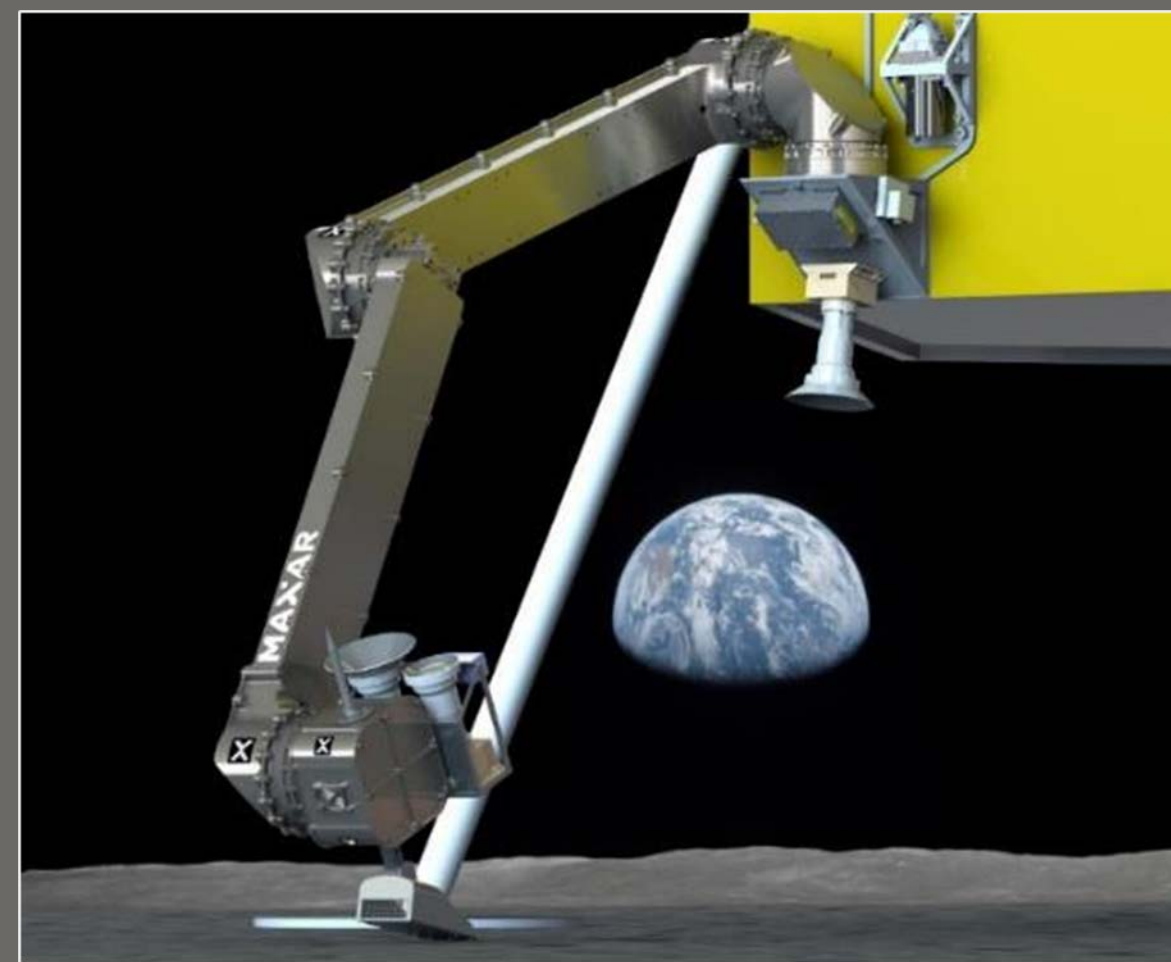


Broad Experience with Automated Systems



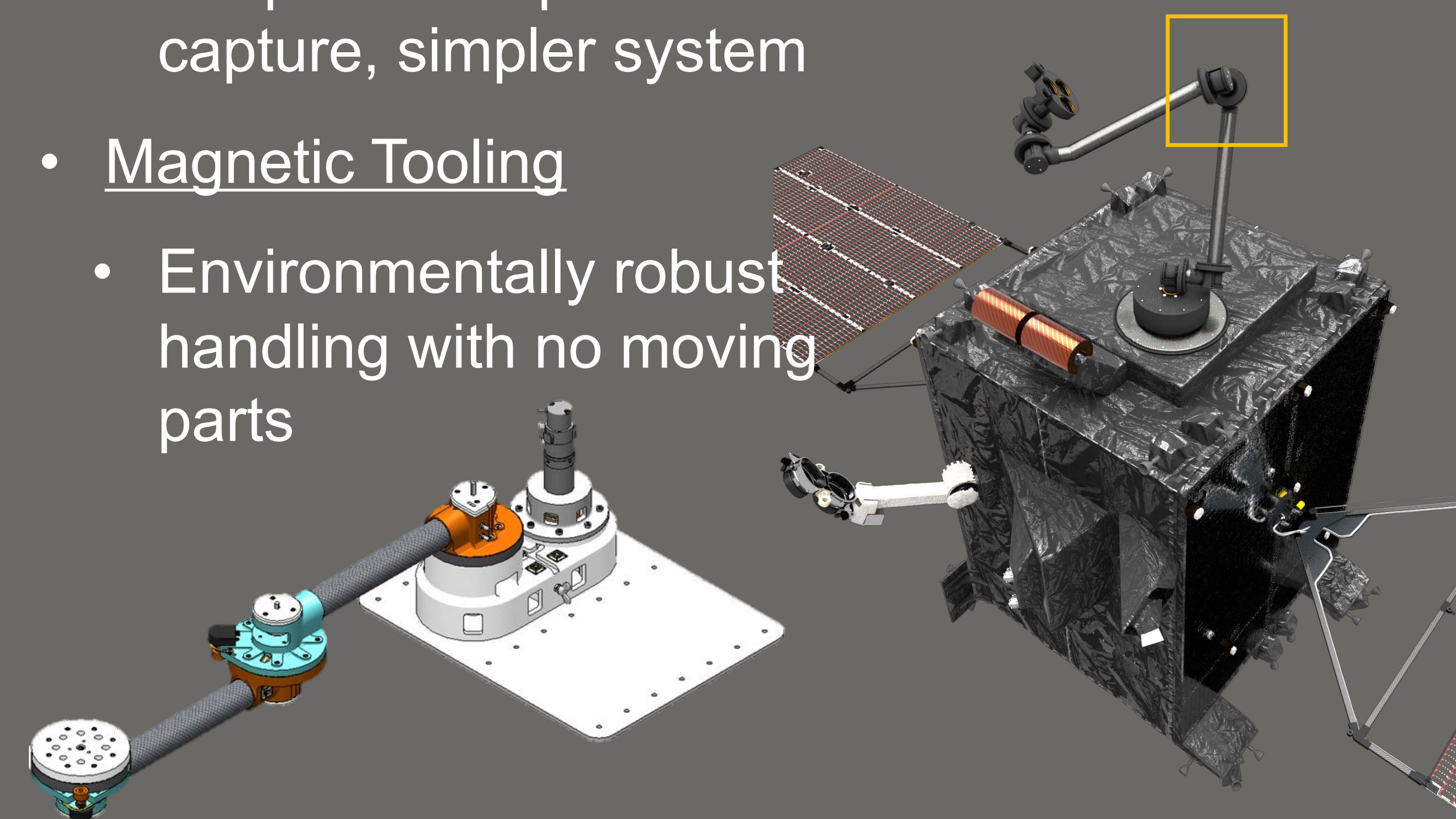
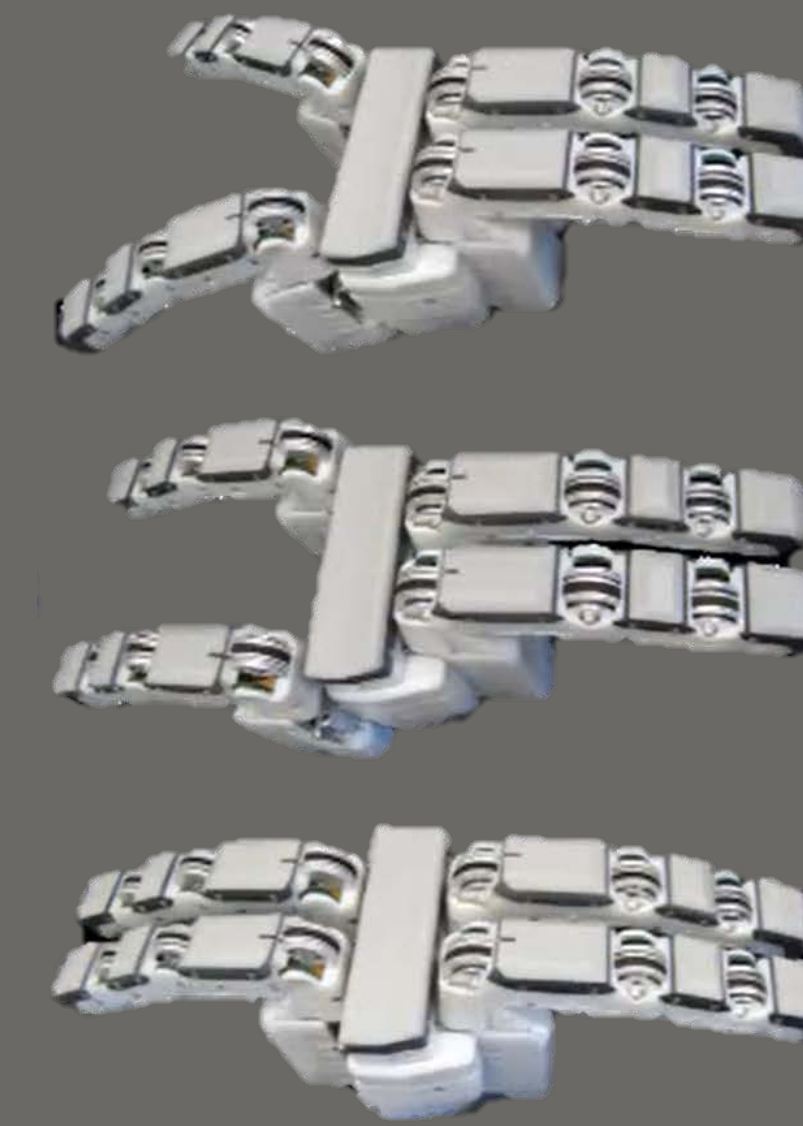
SAMPLR

- Overview
 - Productized Commercial Robotic Manipulator, Enables:
 - Affordable, rapid development
 - Planetary exploration/science
 - Fully integrated (bolt-on) system
 - Commercially operated
- Modular Capabilities:
 - 0.5 to 2+ meter reach
 - 25+ kg payload
 - 4-7 Degrees of Freedom
 - Force/torque sensing
 - 1mm precision
- Mission Capabilities
 - 4 Degrees of Freedom
 - 14 kg arm, 1.5 m reach
 - Avg 28 W, Peak 45 W
 - Landing in 2023



LUnA

- Overview
 - New technology to reduce system cost and mass
 - Better environmental protection
 - TRL6 by 2023
- Under-Actuated Architecture
 - One motor drives many joints
- Electro-Adhesive Brakes
 - Light and powerful, to minimize system mass
- Electro-Adhesive Capture
 - Simplifies cooperative capture, simpler system
- Magnetic Tooling
 - Environmentally robust handling with no moving parts



LVSAT

- Overview
 - An autonomously deployable and relocatable 10 kW solar array for lunar surface operations.
 - Leveraging our Mars surface experience, high-reliability commercial satellite components, and advanced technology from NASA and industry partners.
- Deployable Composite Boom
 - Forms the main vertical mast
 - Superior packing factor, high stiffness, best in class mass, excellent thermal stability.
- Electrodynamic Dust Shield
 - Uses electrical fields to protect moving parts from lunar dust intrusion.
- 5J IMM- α Solar Cells
 - Highest efficiency space solar cell in production, 32% minimum average.

