

How can we help?

NavAbility is simplifying mapping & localization software by fostering an open **community**, reducing barriers for **industry**, and always improving the **technology**.



The NavAbility Company helps diverse customers overcome their navigation AI challenges with our **software platform** and expert services.

We define **Navigation AI** as data fusion, calibration, localization, surveying, mapping, tracking, and perception from multi-sensor / prior data.

Innovations

EASE-OF-USE

- ❑ NavAbilitySDKs are ready to integrate
- ❑ Code **examples** to accelerate
- ❑ Core solver is **open-source**, [Caesar.jl](#)
- ❑ Flexible and **extensible**

DISTRIBUTED

- ❑ Data **persistence**
- ❑ **Anywhere** solve and retrieval
- ❑ Designed for **small proof** to hyperscale

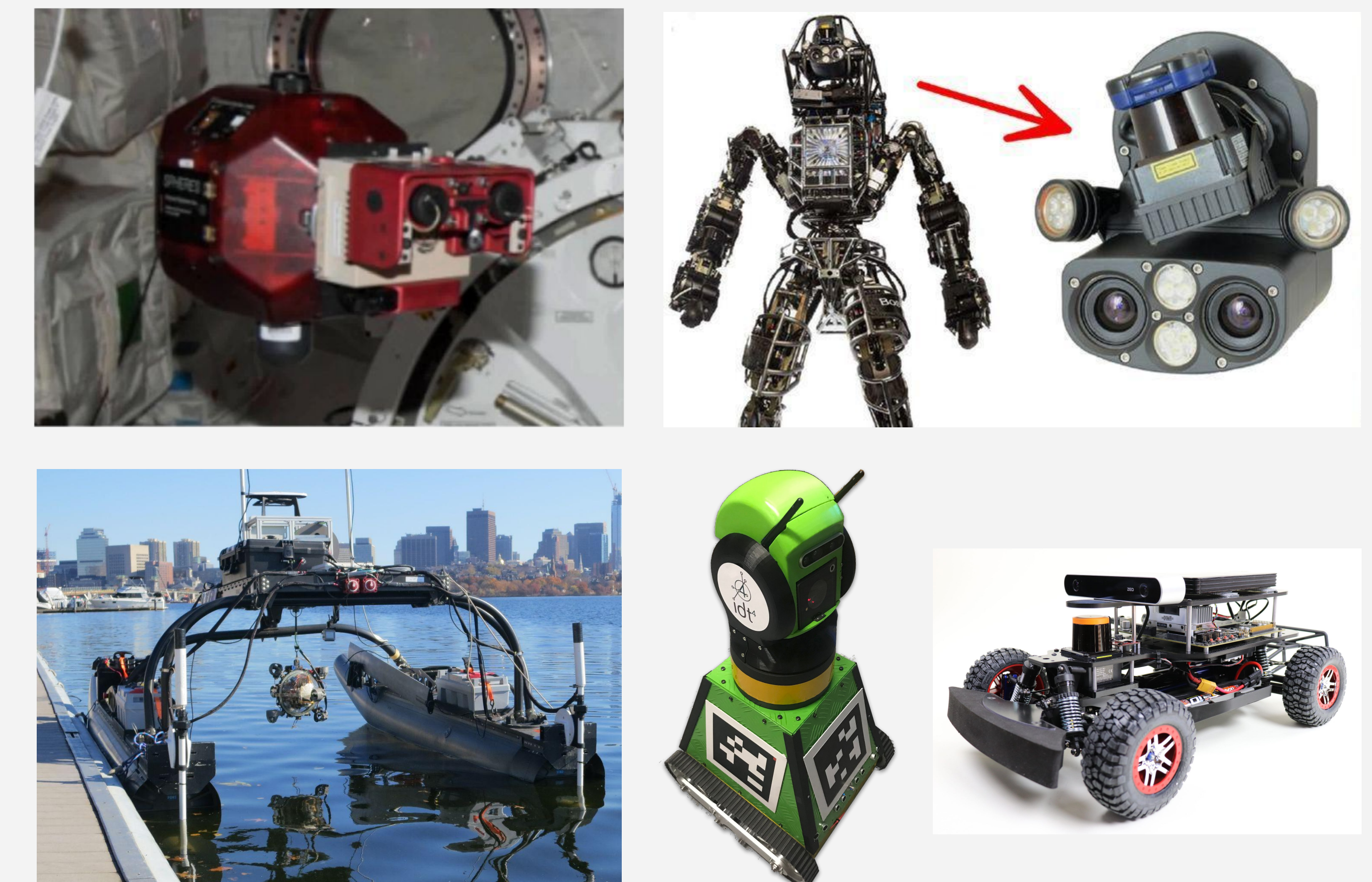
ROBUSTNESS

- ❑ **Non-Gaussian** Algorithms (MIT)
- ❑ Less statistical assumptions
- ❑ Community amplifies quality
- ❑ Open-source **transparency and access**

Application Examples

Terrestrial, Marine, Sub-sea, Aerial, Space

- ❑ <https://www.navability.io/applications/>
- ❑ <https://juliarobotics.org/Caesar.jl/latest/examples/examples/>
- ❑ <https://juliarobotics.org/Caesar.jl/latest/refs/literature/>



Value



Lower cost of ownership:
Development, support,
and consumption

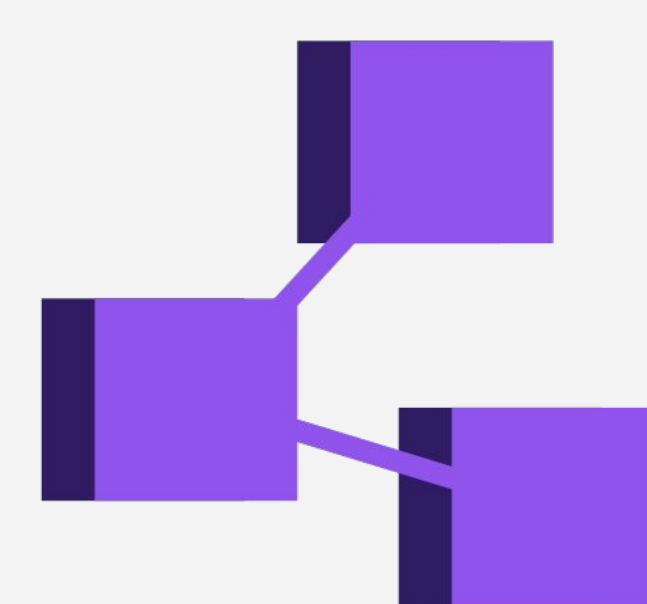


Faster time to market:
NavAbility Products

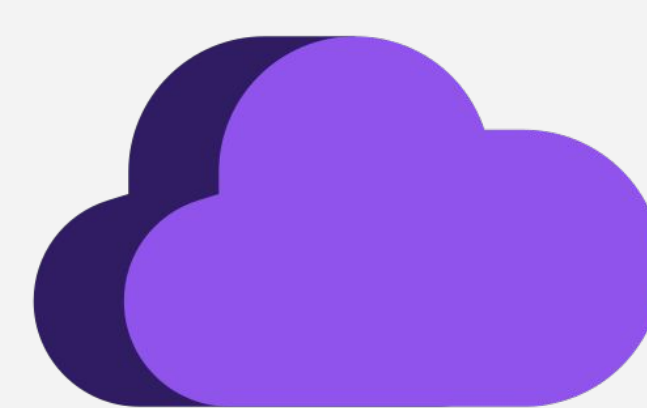


Reduced project risk:
NavAbility Expertise

Products



Open-source libraries,
Rapid prototyping,
Always **free** to use

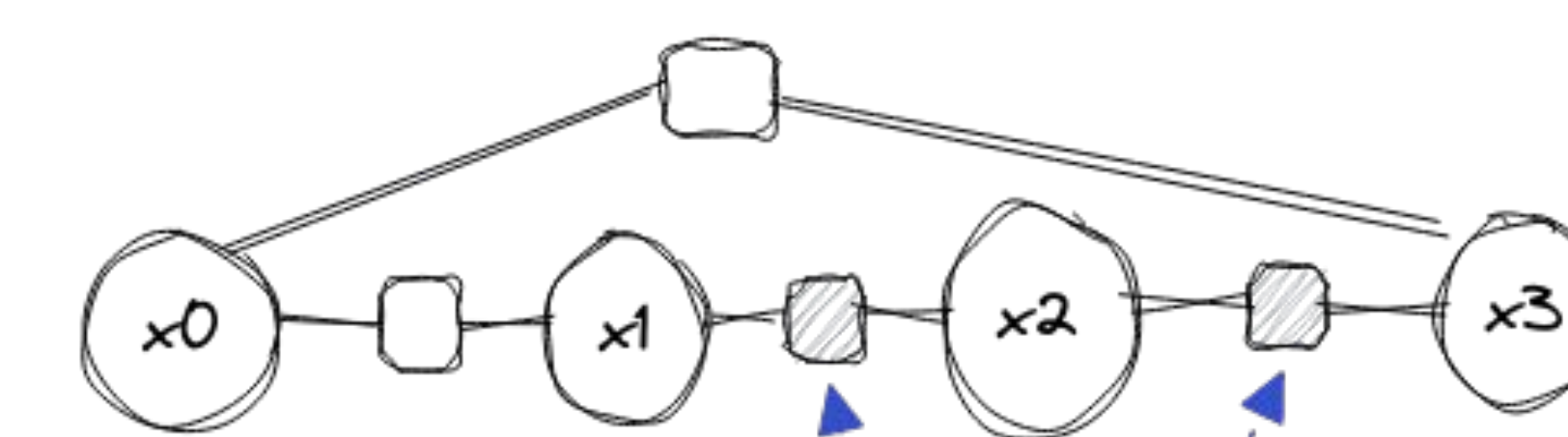


NavAbility Platform
Cloud API & SDKs
Distributed, hybrid design

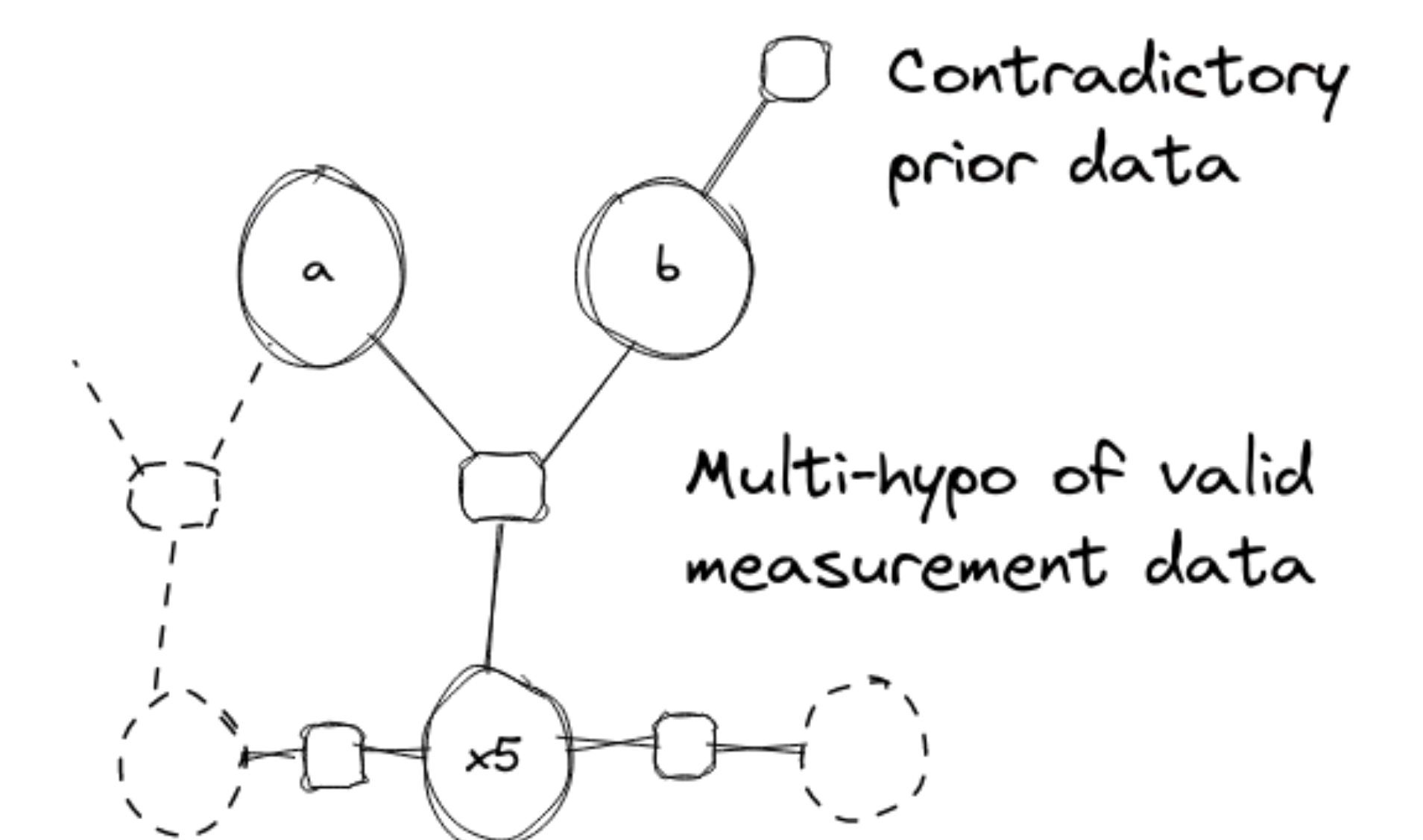


NavAbility **Expertise**
Ongoing Support / Fixes
Accelerated development

Try the Tutorials



Non-Gaussian
Measurement data



Multi-hypo of valid
measurement data

Contradictory
prior data